

Magnetically-assisted Vorticity Production in Decaying Acoustic Turbulence

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ABSTRACT

We study vorticity production in isothermal, subsonic, acoustic (nonvortical), decaying turbulence due to the presence of magnetic fields. Using three-dimensional numerical simulations, we find that the resulting turbulent kinetic energy cascade follows the ordinary Kolmogorov phenomenology involving a constant spectral energy flux. The nondimensional prefactor for acoustic turbulence is larger than the standard Kolmogorov constant due to the inefficient dissipation of kinetic energy. We find that the Lorentz force can drive vortical motions even when the initial field is uniform, by converting a fraction of the acoustic energy into vortical energy. This conversion is shown to be quadratic in the magnetic field strength and linear in the acoustic flow speed. By contrast, the direct production of vortical motions by the magnetic field is linear in the field strength. Our results suggest that magnetic fields play a crucial role in vorticity production in cosmological flows, particularly in scenarios where significant acoustic turbulence is prevalent. We also discuss the implications of our findings for the early universe, where magnetic fields may convert acoustic turbulence generated during cosmological phase transitions into vortical turbulence.

Keywords: Astrophysical magnetism (321) — Plasma astrophysics (1261)

1. INTRODUCTION

One can envisage diverse astrophysical situations where the velocity field is irrotational and the gas motions are predominantly acoustic. Such flows can be described as the gradient of a potential function and thus may arise hydrodynamically from gradients of the gravitational potential or of barotropic pressure fluctuations.

Vortical motions, on the other hand, arise hydrodynamically through shocks (Porter et al. 2015) and through the baroclinic term (Del Sordo & Brandenburg 2011; Federrath et al. 2011; Jahanbakhshi et al. 2015; Elias-López et al. 2023, 2024) resulting from oblique gradients of density and pressure. However, the efficiency of these effects is limited because they depend on the Mach number, which is often small, and thus thermal effects such as differential heating may be too weak to produce baroclinicity.

On the other hand, it has been known for some time that magnetic fields create vorticity regardless of the possible presence of irrotational turbulence as long as the curl of the Lorentz force is nonvanishing. This was demonstrated by Kahnishvili et al. (2012), who were

primarily interested in the effect of turbulence from cosmological phase transitions on an inflationary-generated magnetic field. Yet the possibility of producing vorticity in the presence of magnetic fields is more general and may also have occurred under other circumstances.

A characteristic property of vortical turbulence is the constancy of the energy flux from the driving scale along the turbulent cascade down to the dissipation scale. This allows one to express the energy spectrum in nondimensional form, yielding a dimensionless prefactor known as the Kolmogorov constant (Frisch 1995; Sreenivasan 1995), which is well measured in vortical turbulence. There have been numerous studies of acoustic turbulence starting with the early works of Kadomtsev & Petviashvili (1973), Elsasser & Schamel (1974, 1976), and L'vov & Mikhailov (1981). However, many subsequent studies focused on compressibility effects (Passot & Pouquet 1987; Shivamoggi 1992; Cho & Lazarian 2005; Galtier & Banerjee 2011). Although also the spectral properties of acoustic turbulence have been investigated in some detail (Falkovich & Meyer 1996; Kuznetsov & Krasnoselskikh

2008; Kochurin & Kuznetsov 2022; Ricard & Falcon 2023), no values for a Kolmogorov-like prefactor have been quoted for magnetized acoustic turbulence.

Here, we use numerical simulations to revisit magnetic vorticity production in acoustic turbulence, focusing on three main questions. (1) Can the Kolmogorov prefactor be determined for acoustic turbulence and how does the presence of a magnetic field change its value? (2) To what extent does magnetically modified acoustic turbulence resemble ordinary turbulence? (3) Can the kinetic energy of acoustic turbulence be converted into that of vortical turbulence due to the presence of a magnetic field?

We emphasize that we are not concerned with strong compressibility effects, which would occur at large Mach numbers (Schleicher et al. 2013; Federrath et al. 2014; Porter et al. 2015). This is why we prefer the term acoustic (Kadomtsev & Petviashvili 1973) over compressive. Furthermore, compared to the more general term irrotational, the term acoustic is more directly suggestive of low amplitude subsonic flows.

The structure of this work is as follows. In §2 we describe the MHD equations and their implications for vorticity production, as well as our numerical approach, parameter space, and approach to analyzing the runs. In §3 we present our results focusing on measurements of the Kolmogorov prefactor and magnetic vorticity production. Implications and conclusions are given in §4.

2. THE MODEL

2.1. Basic Equations

We solve the hydrodynamic and magnetohydrodynamic (MHD) equations with an isothermal equation of state, where the pressure p and the density ρ are related to each other through $p = \rho c_s^2$ with $c_s = \text{const}$ being the isothermal speed of sound. This precludes vorticity production by the baroclinic term. The evolution equations for ρ and the velocity \mathbf{u} are then given by

$$\frac{D \ln \rho}{Dt} = -\nabla \cdot \mathbf{u}, \quad \text{and} \quad (1)$$

$$\frac{D\mathbf{u}}{Dt} = -c_s^2 \nabla \ln \rho + \frac{\mathbf{J} \times \mathbf{B}}{\rho} + \mathbf{F}_{\text{visc}}, \quad (2)$$

where \mathbf{B} is the magnetic field, $\mathbf{J} = \nabla \times \mathbf{B} / \mu_0$ is the current density with μ_0 being the vacuum permeability, $\mathbf{J} \times \mathbf{B}$ is the Lorentz force, $\mathbf{F}_{\text{visc}} = \rho^{-1} \nabla \cdot (2\nu \rho \mathbf{S})$ is the viscous force per unit mass with ν being the kinematic viscosity, and \mathbf{S} the rate-of-strain tensor with components $S_{ij} = \frac{1}{2}(\partial_i u_j + \partial_j u_i) - \frac{1}{3} \delta_{ij} \nabla \cdot \mathbf{u}$. Note that our simulations only include the usual shear viscosity and assume that the bulk viscosity is absent; see Beattie et al. (2023) for a recent work on this aspect.

In simulations in which the magnetic field is included, we also solve for the magnetic potential \mathbf{A} via

$$\frac{\partial \mathbf{A}}{\partial t} = \iota \mathbf{u} \times \mathbf{B} + \eta \nabla^2 \mathbf{A}, \quad (3)$$

so that $\nabla \times \mathbf{A}$ is always divergence-free. In several of our models, we also impose an external magnetic field \mathbf{B}_0 by writing $\mathbf{B} = \mathbf{B}_0 + \nabla \times \mathbf{A}$, so that we can adopt periodic boundary conditions on \mathbf{A} . In Equation (3), the parameter ι is introduced to allow us to turn off the induction term ($\iota = 0$). By default, we have $\iota = 1$.

2.2. Vorticity Production

To understand the terms leading to vorticity production, we take the curl of Equation (2) and find

$$\frac{\partial \mathbf{w}}{\partial t} = \nabla \times (\mathbf{u} \times \mathbf{w}) + \dot{\mathbf{w}}_{\text{mag}} + \dot{\mathbf{w}}_{\text{visc}}, \quad (4)$$

where $\dot{\mathbf{w}}_{\text{mag}} = \nabla \times (\mathbf{J} \times \mathbf{B} / \rho)$ is the magnetically-produced vorticity and $\dot{\mathbf{w}}_{\text{visc}} = \nabla \times \mathbf{F}_{\text{visc}}$ is the viscously produced vorticity. Under the assumption that $\nu = \text{const}$, we find (Mee & Brandenburg 2006)

$$\dot{\mathbf{w}}_{\text{visc}} = \nu \nabla^2 \mathbf{w} + \nu \nabla \times \mathbf{G} \quad (\nu = \text{const}), \quad (5)$$

where $G_i = 2S_{ij} \nabla_j \ln \rho$ is a term that always drives vorticity—even if it is initially absent. Alternatively, if $\mu \equiv \nu \rho = \text{const}$, we have $\mathbf{F}_{\text{visc}} = \rho^{-1} \mu (\nabla^2 \mathbf{u} + \frac{1}{3} \nabla \nabla \cdot \mathbf{u})$ and

$$\dot{\mathbf{w}}_{\text{visc}} = \frac{\mu}{\rho} \left[\nabla^2 \mathbf{w} + \nabla \ln \rho \times (\nabla \times \mathbf{w} - \frac{4}{3} \nabla \nabla \cdot \mathbf{u}) \right], \quad (6)$$

when $\mu = \text{const}$. This expression shows that viscous vorticity production results from the obliqueness of density and velocity divergence gradients, which is somewhat analogous to vorticity production by a baroclinic term in the non-isothermal case. The $1/\rho$ term in the expression for $\dot{\mathbf{w}}_{\text{mag}}$ is generally only of minor importance when the Mach number is small. Thus in the following, we focus on the case $\nu = \text{const}$, where vorticity production occurs through similar terms as in the case $\mu = \text{const}$.

While $\dot{\mathbf{w}}_{\text{visc}}$ can play a role at small scales, it is not the only term that can convert acoustic motions into vortical motions in a magnetized flow. This is because acoustic flows modify the magnetic field, which may then exert a Lorentz force with a finite curl. We refer to this as magnetically-assisted vorticity production. We give a simple one-dimensional example of this process in Sect. 3.6.1, and in Sect. 3.6.2 we present a set of simulations that validate the scaling relations obtained from the one-dimensional model.

2.3. Summary of the Runs

We use the **PENCIL CODE** (Pencil Code Collaboration et al. 2021), which employs sixth-order centered differences and a third-order timestepping scheme. In all cases, we use a resolution of 1024^3 mesh points. Our simulations have periodic boundary conditions, so the mass in the volume is conserved and the mean density $\rho_0 \equiv \langle \rho \rangle$ is constant. Here and below, angle brackets denote volume averaging.

Our initial velocity and vector potential are constructed in Fourier space as $\mathbf{u}(\mathbf{x}) = \sum \tilde{\mathbf{u}}(\mathbf{k}) e^{i\mathbf{k}\cdot\mathbf{x}}$ and $\mathbf{A}(\mathbf{x}) = \sum \tilde{\mathbf{A}}(\mathbf{k}) e^{i\mathbf{k}\cdot\mathbf{x}}$ with

$$\tilde{u}_i(\mathbf{k}) = \left[(1 - \zeta)\delta_{ij} - (1 - 2\zeta)\hat{k}_i\hat{k}_j \right] u_{\text{ini}}\tilde{S}_j(\mathbf{k}), \quad (7)$$

$$\tilde{A}_i(\mathbf{k}) = \left(\delta_{ij} - \hat{k}_i\hat{k}_j \right) A_{\text{ini}}\tilde{S}_j(\mathbf{k}). \quad (8)$$

Here, u_{ini} and A_{ini} are amplitude factors, \hat{k}_i are the components of the unit vector $\hat{\mathbf{k}} \equiv \mathbf{k}/k$, $\tilde{S}_j(\mathbf{k})$ is a vector field in Fourier space with three independent components that depend on $k = |\mathbf{k}|$, but have random phases $\varphi(\mathbf{k})$ for each \mathbf{k} vector, and ζ is the irrotationality parameter with $\zeta = 0$ when the initial velocity is vortical and $\zeta = 1$ when it is acoustic (irrotational). Here we choose

$$\tilde{S}_j(\mathbf{k}) = \frac{k_0^{-3/2}(k/k_0)^{\alpha/2-1}}{1 + (k/k_0)^{(\alpha+5/3)/2}} e^{i\varphi(\mathbf{k})}, \quad (9)$$

where k_0 is the peak wavenumber of the initial condition and α is the slope of the subinertial range, which we set to $\alpha = 4$ in this work.

2.4. Diagnostic Quantities

An important characteristic of turbulence is its energy spectrum. The kinetic energy density per linear wavenumber interval, $E_K(k, t)$, is defined as the modulus squared of the Fourier transform of the velocity integrated over concentric shells in wavevector space. The spectrum is normalized such that $\mathcal{E}_K(t) = \int E_K(k, t) dk$ is the mean kinetic energy density. To obtain the energy per unit volume, we include a ρ_0 factor, so $\mathcal{E}_K(t) = \rho_0 \langle \mathbf{u}^2 \rangle / 2$, but we refer the reader to Kritsuk et al. (2007) for alternatives.

The magnetic energy spectrum $E_M(k, t)$ is defined analogously such that $\mathcal{E}_M(t) = \int E_M(k, t) dk$ is the mean magnetic energy density with $\mathcal{E}_M(t) = \langle \mathbf{B}^2 \rangle / 2\mu_0$. In addition, we also compute the spectrum of the vorticity, $E_w(k, t)$, analogously to $E_K(k, t)$, but with the velocity \mathbf{u} being replaced by the vorticity $\mathbf{w} = \nabla \times \mathbf{u}$. In this case $E_w(k, t)$ is related to the vortical part of the kinetic energy spectrum, $E_V(k, t)$, through $E_V(k, t) = E_w(k, t)/k^2$.

Finally, we also consider the scaled logarithmic density spectrum, $E_{\ln\rho}(k, t)$, which is normalized such that $\int E_{\ln\rho}(k, t) dk = \rho_0 \langle (c_s \ln\rho)^2 \rangle / 2$. Looking at Equation (1), the spatio-temporal Fourier transform of its linearized form reads $-i\omega \widetilde{\ln\rho} = -i\mathbf{k} \cdot \tilde{\mathbf{u}}$, where ω is the frequency. Using the dispersion relation for sound waves, $\omega = c_s k$, we have $c_s \widetilde{\ln\rho} = \hat{\mathbf{k}} \cdot \tilde{\mathbf{u}}$, so that $c_s \ln\rho$ is directly a proxy for the longitudinal velocity, and $E_{\ln\rho}(k, t)$ is a proxy of the energy spectrum of the acoustic part, $E_A \approx E_{\ln\rho}$. We note that $E_K = E_V + E_A$ is a fairly accurate decomposition, at least for subsonic flows. We therefore compute the acoustic velocity spectrum as $E_A = E_K - E_V$, and have verified that $E_{\ln\rho}$ is indeed a good approximation of E_A .

The kinetic and magnetic dissipation rates are

$$\epsilon_K \equiv \langle 2\nu\rho\mathbf{S}^2 \rangle, \quad \text{and} \quad \epsilon_M \equiv \langle \eta\mu_0\mathbf{J}^2 \rangle, \quad (10)$$

respectively. The magnetic dissipation can also be obtained from $\epsilon_M(t) = \int 2\eta k^2 E_M(k, t) dk$. For the kinetic energy dissipation, however, we have to remember that vortical and irrotational parts contribute differently, because

$$\langle \mathbf{S}^2 \rangle = \langle \mathbf{w}^2 \rangle + \frac{4}{3} \langle (\nabla \cdot \mathbf{u})^2 \rangle. \quad (11)$$

Therefore, we also define $\epsilon_V(t) = \int 2\nu k^2 E_V(k, t) dk$, and $\epsilon_A(t) = \frac{4}{3} \int 2\nu k^2 E_A(k, t) dk$, but note that, in general, $\epsilon_K \neq \epsilon_V + \epsilon_A$ owing to the existence of mixed terms.

To characterize the velocity and magnetic fields of our runs, we define five different Mach numbers. The usual Mach number is $\text{Ma} = u_{\text{rms}}/c_s$, which characterizes the combined vortical and acoustic parts. These can also be characterized separately through $\text{Ma}_V = \sqrt{2\mathcal{E}_V}/\rho_0/c_s$ and $\text{Ma}_A = \sqrt{2\mathcal{E}_A}/\rho_0/c_s$, so that $\text{Ma}^2 = \text{Ma}_V^2 + \text{Ma}_A^2$. The magnetic field is characterized by the Alfvén speed $v_A = B_{\text{rms}}/\sqrt{\rho_0\mu_0}$, which allows us to define a corresponding Mach number. Here, it is convenient to consider separately the contributions from the imposed field $v_{A0} = \mathbf{B}_0/\sqrt{\rho_0\mu_0}$ and the rest, v_{A1} , so that $v_A^2 = v_{A0}^2 + v_{A1}^2$. The corresponding Mach numbers are then $\text{Ma}_{M0} = v_{A0}/c_s$ and $\text{Ma}_{M1} = v_{A1}/c_s$.

We also define the time-dependent Reynolds number $\text{Re} = u_{\text{rms}}\xi_K/\nu$ based on the usual integral scale

$$\xi_K = \int k^{-1} E_K(k) dk / \mathcal{E}_K \quad (12)$$

and quote in the following a late-time average when it varies only slowly. In all cases, our Mach numbers are averaged over a fixed interval at a time of around one hundred sound travel times, $(c_s k_1)^{-1}$. The values of the Mach numbers are well below unity. The magnetic Prandtl number, $\text{Pr}_M = \nu/\eta$, is taken to be unity in all cases.

Table 1. Summary of the runs discussed in this paper. Columns show the run name (column 1), irrotationality parameter ζ (column 2), induction switch ι (column 3), normalized peak wavenumber $\tilde{k}_0 = k_0/k_1$ (column 4), normalized amplitudes of initial velocity and vector potential, $\tilde{u}_{\text{ini}} = u_{\text{ini}}/c_s$ and $\tilde{A}_{\text{ini}} = k_1 A_{\text{ini}}/\sqrt{\rho_0 \mu_0} c_s$ characterize the initial random velocity and magnetic vector potential (columns 5 and 6), five different Mach numbers (columns 7–11), Reynolds number (column 12), and six different Kolmogorov-type parameters (columns 13–18). Dashes indicate that C_M cannot be determined for nonmagnetic runs. Run D is the same as Run C, except that the induction term has been ignored in Equation (3).

Run	input parameters						output parameters										
	ζ	ι	\tilde{k}_0	\tilde{u}_{ini}	\tilde{A}_{ini}	Ma_{M0}	Ma_{M1}	Ma_{K}	Ma_{V}	Ma_{A}	Re	C_{M}	C_{K}	C_{KV}	C_{KA}	C_{V}	C_{A}
A	0	1	10	0.020	0	0	0	0.020	0.020	0.002	1200	—	1.62	1.62	0.00	1.65	0.00
B	1	1	10	0.020	0	0	0	0.013	0.000	0.013	1000	—	6.06	0.00	6.06	0.35	6.06
C	1	1	10	0.020	0.005	0	0.009	0.014	0.004	0.013	1100	2.93	6.31	0.33	5.99	0.80	7.22
D	1	0	10	0.020	0.005	0	0.019	0.033	0.031	0.010	1200	0.00	1.86	1.65	0.22	1.69	0.48
E	0	1	10	0	0.005	0	0.008	0.003	0.003	0.000	200	2.88	0.96	0.96	0.00	0.96	0.02
F	1	1	10	0.020	0	1.00	0.010	0.014	0.008	0.012	200	3.66	3.92	1.57	2.35	3.09	3.17
G	1	1	2	0.020	0.005	0	0.014	0.013	0.007	0.011	2100	1.80	6.58	0.86	5.72	1.54	7.36
H	1	1	2	0.020	0	0	0	0.026	0.000	0.026	1300	—	2.17	0.00	2.17	0.26	2.18
I	1	1	2	0.020	0	0.02	0	0.026	0.000	0.026	1900	0.19	2.26	0.00	2.26	0.18	2.27
J	1	1	2	0.020	0	0.05	0.001	0.026	0.000	0.026	1900	0.35	2.26	0.00	2.26	0.32	2.28
K	1	1	2	0.020	0	0.10	0.002	0.026	0.001	0.026	1500	0.57	2.13	0.00	2.12	0.74	2.13
L	1	1	2	0.020	0	0.20	0.004	0.026	0.001	0.026	1300	0.98	2.11	0.02	2.09	1.39	2.09
M	1	1	2	0.020	0	0.50	0.011	0.026	0.005	0.025	1900	1.95	2.47	0.17	2.30	2.18	2.35
N	1	1	2	0.020	0	1.00	0.020	0.028	0.015	0.023	1900	2.92	3.13	1.01	2.12	2.32	2.67
O	1	1	2	0.004	0	0.10	0.001	0.008	0.000	0.008	500	0.63	2.74	0.00	2.74	0.16	2.76
P	1	1	2	0.004	0	1.00	0.006	0.008	0.004	0.007	500	2.90	3.12	0.55	2.57	1.99	2.87

It is convenient to present magnetic and kinetic energy spectra in normalized form. Instead of normalizing them by a quantity characterizing the large-scale properties ($\mathcal{E}_{\text{K}}/k_0$), we choose here to normalize them by the quantity $\epsilon_{\text{K}}^{2/3}/k_0^{5/3}$ characterizing the small scales. For our runs, we take the values $k_0/k_1 = 10$ and 2.

3. RESULTS

3.1. Summary of the Runs

We have performed a series of runs varying the input parameters ζ , ι , k_0 , u_{ini} , A_{ini} , Ma_{M0} , and Ma_{M1} ; see Table 1 for a summary. Nonmagnetic runs are those where $\text{Ma}_{\text{M0}} = \text{Ma}_{\text{M1}} = 0$ (see Runs A, B, and H). When $\text{Ma}_{\text{M0}} = 0$, but $\text{Ma}_{\text{M1}} \neq 0$, we have initially a random (‘turbulent’) magnetic field with a spectrum peaking at $k \approx k_0$, similarly as for the initial velocity field (Runs C–E and G). Run D is the same as Run C, except that the induction term has been ignored in Equation (3), i.e., $\iota = 0$. The Mach numbers are in the range 0.007–0.04 and the Reynolds number is in the range 200–1900.

The Kolmogorov-type parameter or prefactor for the magnetic field, C_{M} , varies significantly and is usually in the range 2–8. In all cases with $\zeta \neq 0$, C_{K} exceeds the typical value of 1.6 for vortical turbulence (Run A). Almost no vorticity is produced when Ma_{K} and C_{KV} are small (Runs B, C, H–L, and O). This is the case

for all nonmagnetic and weakly magnetized cases when $\text{Ma}_{\text{M0}} \lesssim 0.1$. Vorticity is being produced when $\text{Ma}_{\text{M0}} \gtrsim 0.01$ or $\text{Ma}_{\text{M1}} \gtrsim 0.02$ (Run C–E and G). We recall that Run G has a smaller value of k_0 than Run C–E.

3.2. Comparison of Typical Spectra

The velocity spectra for Run A, with vortical hydrodynamic turbulence, Run B, with acoustic hydrodynamic turbulence, and Run C, with acoustic MHD turbulence, are compared at a fixed time in Figure 1. We see that, although our runs have a fixed viscosity ($\nu k_1/c_s = 10^{-6}$ for $k_0/k_1 = 10$ and $\nu k_1/c_s = 5 \times 10^{-6}$ for $k_0/k_1 = 2$), and similar values of the Mach Number, only Run A has a spectrum that still possesses significant energy at large k . It is also the only run with a marked bottleneck, i.e., a shallow part just before the viscous subrange at large k (Falkovich 1994). The peak of the scaled spectra for Run B is higher, reflecting the fact that the Kolmogorov prefactor for acoustic turbulence is larger, as we discuss below. Finally, the kinetic energy spectra for Run B and C are similar to that for Run A, except that there is no visible bottleneck.

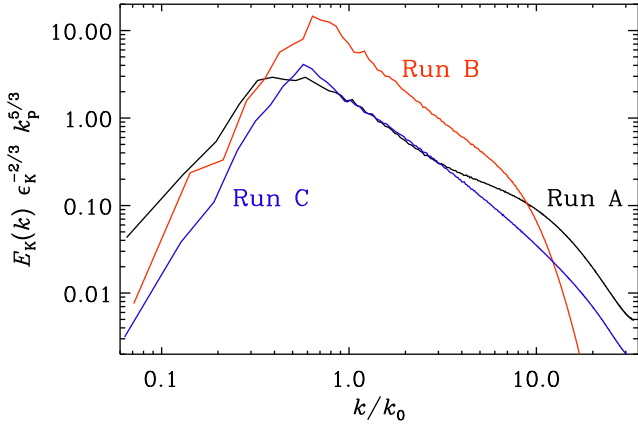


Figure 1. Kinetic energy spectra for Runs V (black), A (red), and C (blue), all at the time, $t = 28/c_s k_1$. No distinction between vortical and acoustic contributions has been made.

3.3. Kolmogorov Prefactor

299

300 In Kolmogorov theory, the constancy of the kinetic
 301 energy flux along the turbulent cascade makes ϵ_K an
 302 important quantity for dimensional arguments. On di-
 303 mensional grounds, the spectrum should be equal to
 304 $C_K \epsilon_K^{2/3} k^{-5/3}$, where C_K where the dimensionless prefactor
 305 is the Kolmogorov constant (Frisch 1995). To obtain
 306 the value of C_K , it is convenient to present compensated
 307 spectra, $\epsilon_K^{-2/3} k^{5/3} E_K(k, t)$, which should show a constant
 308 plateau in the k range where Kolmogorov scaling
 309 applies. Note that the difference to our normalization
 310 in Figure 1 lies in the fact that there the factor $k_0^{5/3}$
 311 was a constant, but now it is k -dependent.

312 We begin with the more familiar vortical case with
 313 $\zeta = 0$ and no magnetic field ($\mathbf{B} = 0$, Run A). The result
 314 is shown in Figure 2, where we see the approach to a
 315 plateau in the compensated spectrum at the level $C_K \approx$
 316 1.6, which agrees with the usual Kolmogorov constant
 317 (Kaneda et al. 2003; Brandenburg et al. 2023). Near
 318 the dissipative subrange, we also see a strong bulge. This
 319 was already evident from Figure 1 and was characterized
 320 as the bottleneck (Falkovich 1994). It is here signifi-
 321 cantly stronger than for ordinary turbulence, for which
 322 the compensated spectrum at the bottleneck is usually
 323 well below 3 (Kaneda et al. 2003; Haugen et al. 2004;
 324 Brandenburg et al. 2023). This could partially be a con-
 325 sequence of having underresolved the high wavenumbers
 326 at early times.

327 The corresponding case for acoustic turbulence, where
 328 $\zeta = 1$, looks different in many ways. This is shown in
 329 Figure 3, where we plot spectra that are compensated
 330 separately for the vortical and acoustic parts, i.e.,

$$331 \quad c_i(k, t) = \epsilon_i^{-2/3}(t) k^{5/3} E_i(k, t), \quad (13)$$

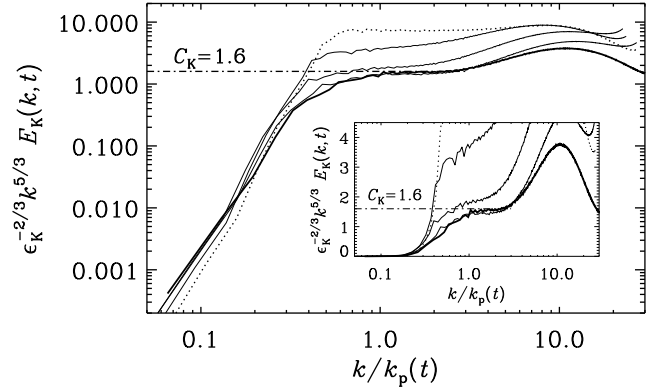


Figure 2. Compensated kinetic energy spectra for Run A at times $c_s k_1 t = 3, 7, 14,$ and 28 . The dotted line denotes the initial state and the thick line marks the last time. The dashed-dotted horizontal line marks the approach to the value $C_K = 1.5$. The inset shows the approach to a plateau in a semilogarithmic plot.

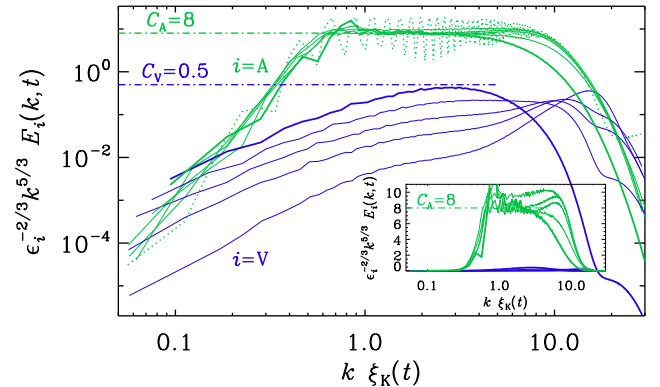


Figure 3. Compensated kinetic energy spectra for acoustic turbulence (Run B), $\epsilon_i^{-2/3}(t) k^{5/3} E_i(k, t)$, separated into the vortical ($i = V$, blue lines) and acoustic ($i = A$, orange lines) components.

332 and denote by C_i the approximate average of $c_i(k, t)$
 333 over the flat part for $i = V$, or A. Here still see the
 334 approach to a plateau, but the bottleneck is very weak
 335 (see the inset). Instead, there is a spike in E_A at the
 336 low wavenumber end, where the spectrum transits from
 337 the subinertial range to the inertial range. In the follow-
 338 ing, we refer to this spike as the subinertial range peak.
 339 The height of the plateau also significantly exceeds the
 340 usual value and is $C_A \approx 8$, suggesting that standard
 341 Kolmogorov scaling may not be applicable.

342 In Run B, some vorticity is produced by the interac-
 343 tion with viscosity. Even though the spectrum in Fig-
 344 ure 3 is normalized by ϵ_A , the level of the plateau is
 345 low (around 0.5), albeit still increasing with time. As
 346 discussed in Sect. 2.1, such vorticity production results

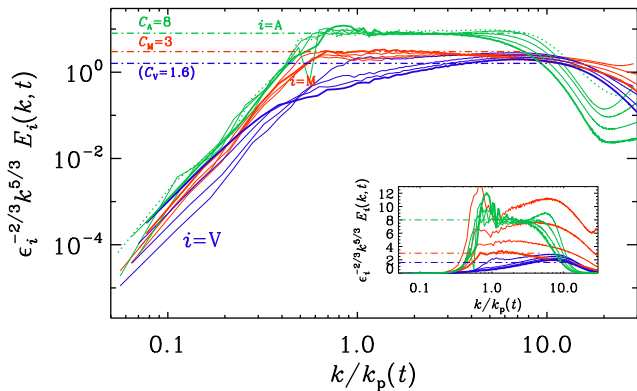


Figure 4. Similar to Figure 3, but for Run C, where the magnetic field produces vorticity. Compensated magnetic energy spectra are also plotted ($i = M$, red lines). The dashed-dotted horizontal lines indicate the approximate positions of plateaus at $C_A \approx 8$ (orange), $C_M = 3$ (red), and $C_V = 2$ (blue).

347 from the obliqueness of density and velocity divergence
348 gradients. We find that the amount of vorticity produc-
349 tion is virtually the same regardless of whether ν or μ are
350 held constant. This is likely because the Mach number
351 is small in both cases, meaning that density fluctuations
352 are small.

3.4. Magnetic Vorticity Production

354 Next, for Run C, we consider an irrotational initial
355 flow ($\zeta = 1$, just like Run B) together with a random initial
356 magnetic field with a spectrum $E_M \propto k^4$ for $k < k_0$
357 and $E_M \propto k^{-5/3}$ for $k > k_0$, just like the initial velocity
358 field. Depending on the relative strengths of the mag-
359 netic and velocity fields, the curl of the Lorentz force can
360 drive vorticity through the \mathbf{w}_{visc} term in Equations (5)
361 and (6).

362 The result for Run C is shown in Figure 4. Inter-
363 estingly, the magnetic energy $E_M(k)$ shows neither a
364 marked bottleneck nor a marked subinertial range peak.
365 The compensated $c_V(k)$ spectrum of Equation (13) does
366 not have a plateau, but it crosses $C_V \approx 1.6$ at inter-
367 mediate wavenumbers. Note, however, that $C_M(t)$ has a
368 plateau with a magnetic Kolmogorov prefactor of about
369 3; see Figure 4.

370 In Appendix 4, we compare spectra for Runs C and
371 E with and without initial turbulence, Runs C and D
372 with and without the induction term, i.e., $\iota = 1$ and 0,
373 respectively, as well as Runs C and G with $k_0/k_1 = 10$
374 and 2, respectively. We see that in Run E, turbulence
375 is gradually being produced. Regarding the presence or
376 absence of the induction term, we see that for Run C the
377 induction term enables the magnetic and kinetic energy
378 cascades to be nearly parallel. This is not the case when

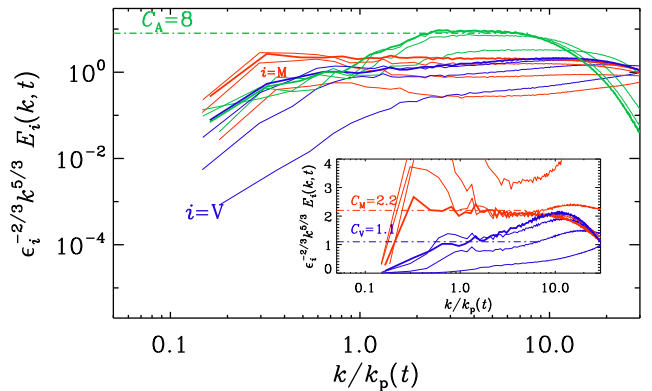


Figure 5. Same as Figure 4, but for Run G with $k_0/k_1 = 2$.

379 the induction term is absent (Run D). Finally, compar-
380 ing Runs C and G, we see that both for $k/k_1 = 2$ and 10,
381 there is a loss of kinetic energy in the acoustic compo-
382 nents along with a gain of kinetic energy in the vortical
383 component.

3.5. Comparison with Earlier Work

384 In the presence of irrotational forcing,
385 Kahniashvili et al. (2012) found that for an infla-
386 tionary magnetic field with a magnetic energy spec-
387 trum proportional to k^{-1} , vortical turbulence develops
388 with a spectrum $E_V(k)$ that is in equipartition, i.e.,
389 $E_V(k) \approx E_M(k)$. Comparing this with our present
390 results, we see that equipartition between $E_V(k)$ and
391 $E_M(k)$ exists only at high wavenumbers. This difference
392 to Kahniashvili et al. (2012) seems to be connected with
393 the fact that they used an inflationary magnetic field
394 with a k^{-1} spectrum, whereas here, $E_M(k)$ has a peak at
395 intermediate wavenumbers. To further verify this inter-
396 pretation, we show in Figure 5 the compensated spectra
397 of $E_V(k, t)$ and $E_M(k, t)$ for a Run with $k_0/k_1 = 2$. We
398 now see that the range over which the two spectra are
399 nearly parallel is not only increased, but also the degree
400 of equipartition is better, i.e., the two spectra are closer
401 together.

402 The velocity spectrum generated by the Lorentz force
403 of such a magnetic field alone, i.e., without an initial
404 acoustic component, is known to develop a shallow spec-
405 trum near k_0 , and is in approximate equipartition with
406 the magnetic field at large wavenumbers. This is similar
407 to the E_V spectrum in Figure 4, where the compen-
408 sated spectra are proportional to $k^{2/3}$, suggesting that
409 $E_V(k) \propto k$ in the beginning of the magnetic inertial
410 range.

411 In agreement with the earlier work of
412 Mee & Brandenburg (2006), the present results con-
413 firm that acoustic turbulence hardly contributes to
414

415 driving magnetic fields. Theoretically, small-scale dy-
 416 namo action of the type first proposed by Kazantsev
 417 (1968) should also be possible for acoustic turbu-
 418 lence (Kazantsev et al. 1985; Martins Afonso et al.
 419 2019), but this has never been confirmed numerically
 420 (Mee & Brandenburg 2006). What has been confirmed,
 421 however, is a small negative turbulent magnetic diffu-
 422 sivity (Rädler et al. 2011). Because its negative value is
 423 never larger than the positive microphysical magnetic
 424 diffusivity, it can only slow down the decay without
 425 leading to dynamo action from this effect alone. Fur-
 426 thermore, this negative turbulent magnetic diffusivity
 427 effect only concerns the mean or large-scale magnetic
 428 field.

3.6. Magnetically-assisted Vorticity Conversion

430 As we have seen from Table 1, runs with suffi-
 431 ciently strong uniform magnetic fields produce notice-
 432 able amounts of vorticity. Here the mechanism causing
 433 vorticity is different from the vorticity production con-
 434 sidered in Sect. 3.4, because here it relies on the pres-
 435 ence of initially acoustic turbulence. This is what we
 436 call magnetically-assisted vorticity conversion. To gain
 437 a better understanding of this conversion mechanism of
 438 acoustic turbulent energy into vortical turbulent energy
 439 due to the presence of a magnetic field, we consider first
 440 a simple one-dimensional example.

3.6.1. Vorticity Conversion in One Dimension

442 The conversion of acoustic kinetic energy into vortical
 443 kinetic energy can be demonstrated with the help of a
 444 one-dimensional example. We consider a domain $-\pi <$
 445 $x < \pi$ with a uniform magnetic field in the diagonal di-
 446 rection, $\mathbf{B}_0 = (B_{0x}, B_{0y}, 0)$, constant density, $\rho = \rho_0$,
 447 and a standing sound wave initially, i.e., $u_x = u_0 \sin kx$.
 448 All the kinetic energy is then in acoustic motions. The
 449 uncurled induction equation reads $\dot{A}_z = u_x B_{0y}$, and the
 450 momentum equation becomes $\dot{\mathbf{u}} = J_z(-B_{0y}, B_{0x}, 0)/\rho_0$,
 451 where dots denote time derivatives. For vorticity pro-
 452 duction, which yields $w_z = u'_y$, where primes denote x
 453 derivatives, only the u_y component matters and thus we
 454 have $\dot{w}_z = J'_z B_{0x}/\rho_0$. Taking another time derivative
 455 and using $J_z = -A''_z$, we have $\ddot{w}_z = -u''''_x v_{Ax} v_{Ay}$, where
 456 v_{Ax} and v_{Ay} are the Alfvén speeds in the x and y
 457 directions, respectively. Replacing t and x derivatives by
 458 factors of ω and k , and using the dispersion relation for
 459 sound waves, $\omega = c_s k$, we find for the vorticity ampli-
 460 tude

$$w_z = (v_{Ax} v_{Ay} / c_s^2) u_0 k. \quad (14)$$

462 For $u_x = u_0 \sin kx$, w_z is proportional to $\cos kx$. In
 463 Figure 6, we show three cases: (i) $u_0 = 0.1$, $B_0 = 0.1$; (ii)
 464 $u_0 = 0.05$, $B_0 = 0.1$; and (iii) $u_0 = 0.1$, $B_0 = 0.05$. We

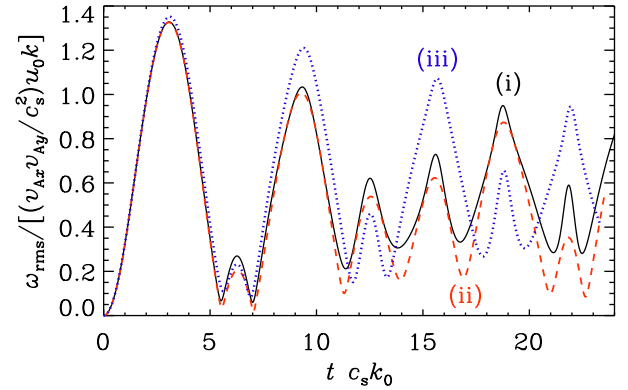


Figure 6. (i) $u_0 = 0.1$, $B_0 = 0.1$; (ii) $u_0 = 0.05$, $B_0 = 0.1$;
 (iii) $u_0 = 0.1$, $B_0 = 0.05$. Note that the normalized curves
 of w_{rms} for all three cases are initially the same.

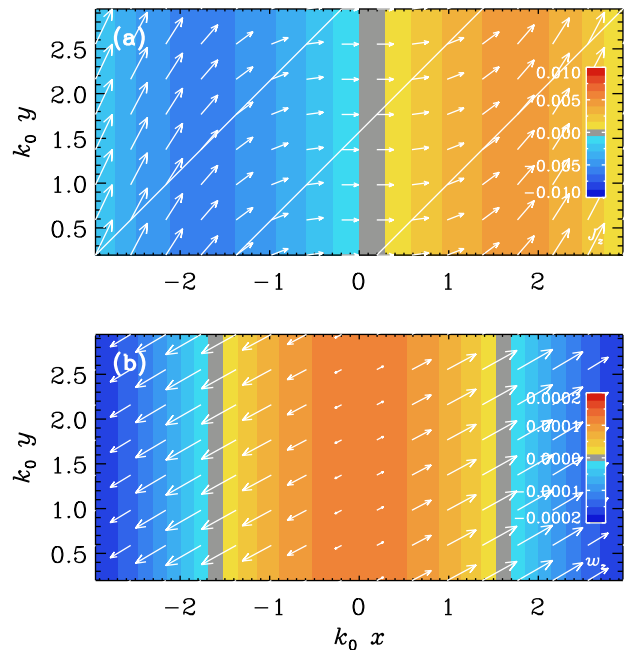


Figure 7. Visualization of (B_x, B_y) vectors overlaid on a
 color-scale representation of J_z (a), and of (u_x, u_y) vectors
 overlaid on w_z (b) in a two-dimensional plane by replicating
 the data of the one-dimensional calculation in the y direction.

465 see that the linear scaling in u_0 and the quadratic scaling
 466 in B_0 in Equation (14) is reproduced by a numerical
 467 simulation of this one-dimensional initial value problem.

468 In Figure 7 we present visualizations of (B_x, B_y) vec-
 469 tors and (u_x, u_y) vectors overlaid on color-scale represen-
 470 tations of J_z and w_z , respectively. To make the small
 471 departures from the uniform field more clearly visible,
 472 we have scaled the perturbations of B_y by a factor of 20
 473 and u_y by a factor of 300.

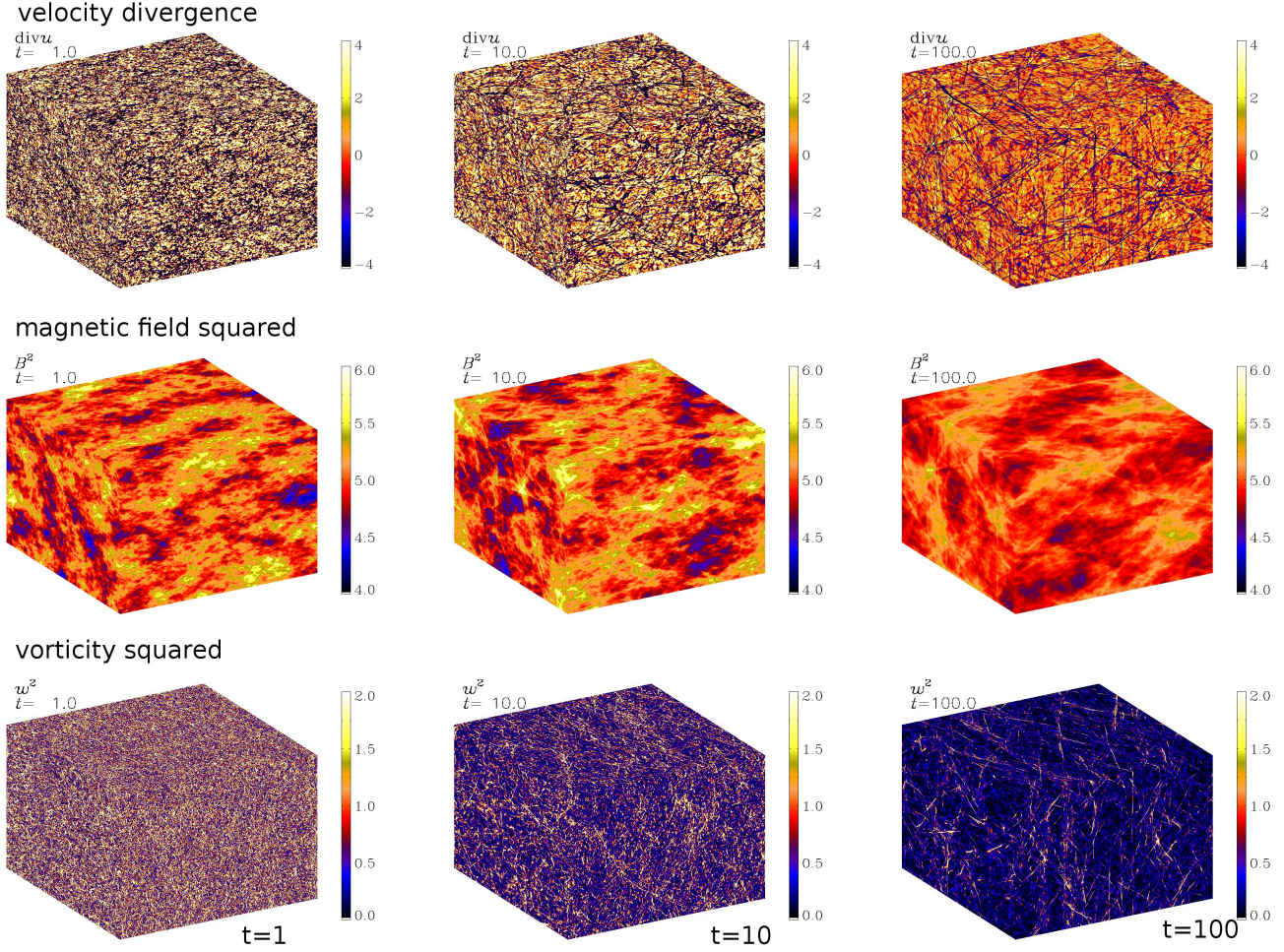


Figure 8. Visualizations of $\nabla \cdot \mathbf{u}$ (top) with a range of -4 to 4 , B^2 (middle) with a range of 4 to 6 , and w^2 (bottom) with a range of 0 to 2 . All plots are on the periphery of the computational domain for Run N at $t c_s k_1 = 1, 10$, and 100 .

474 Given that the magnetically-assisted conversion of
 475 acoustic into vortical motions requires strong fields, it
 476 is of interest to see whether the strength of this conver-
 477 sion can be verified Equation (14). This is done in the
 478 next section.

479 3.6.2. Vorticity Conversion in Three Dimensions

480 To see if the scaling found in Sect. 3.6.1 applies to
 481 our runs, we plot in Figure 9 the dependence of Ma_V
 482 on $\text{Ma}_{M0}^2 \text{Ma}_A$ for runs with an imposed magnetic field.
 483 Except for Runs I–L with $0.02 \leq \text{Ma}_{M1} \leq 0.2$, in which
 484 the magnetic field is weak and the acoustic turbulence
 485 strong, the vorticity obeys the expected scaling with
 486 $\text{Ma}_V \approx 0.67 \text{Ma}_{M0}^2 \text{Ma}_A$. For the runs without an imposed
 487 magnetic field, the same scaling can also be recovered
 488 if we multiply Ma_{M1} by a factor of ≈ 71 , suggesting
 489 that a much weaker turbulent field has the same effect
 490 as a stronger uniform field. Note that it is difficult to
 491 distinguish this type of conversion from vorticity pro-
 492 duced directly from the Lorentz (here Run E). However,

493 we see that the expected dependence on Ma_A is indeed
 494 obeyed; see Equation (14). This suggests that Runs C
 495 and G (green symbols in Figure 9) with $k_0 = 10$ and
 496 2, respectively, with $\text{Ma}_{M0} = 0$ and $\text{Ma}_{M1} = 0.005$ also
 497 experience magnetically-assisted vorticity production.

498 In Figure 8, we present visualizations of $\nabla \cdot \mathbf{u}$, B^2 ,
 499 and w^2 on the periphery of the computational domain
 500 for Run N at three different times. We see that the
 501 structures reflect the presence of shocks extending over
 502 major parts of the domain—especially for the local vor-
 503 ticity density.

504

505 4. CONCLUSIONS

506 Acoustic turbulence is common throughout astro-
 507 physics, arising naturally from gradients of the gravita-
 508 tional potential or of barotropic pressure fluctuations.
 509 In this work, we have used numerical simulations to
 510 study the production of vorticity in isothermal, decay-
 511 ing acoustic turbulence, focusing on the role of magnetic
 512 fields.

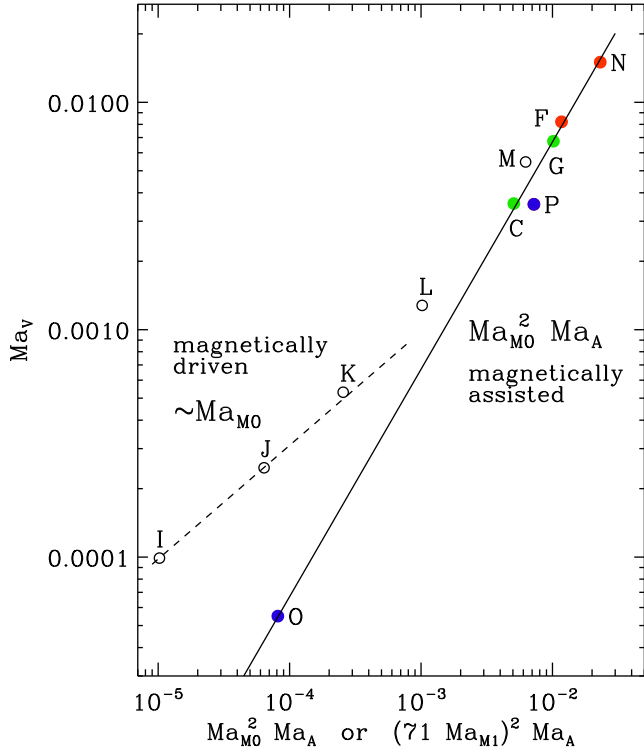


Figure 9. Dependence of Ma_V on $Ma_{M0}^2 Ma_A$ for our three-dimensional runs with an imposed magnetic field, and on $(71 Ma_{M1})^2 Ma_A$ for Runs C and G without imposed magnetic field. The red filled symbols mark Runs F and N, while the green filled symbols mark Runs O and P. The blue filled symbols mark Runs C and G without an imposed magnetic field. The solid line corresponds to $0.67 Ma_{M0}^2 Ma_A$ and the dashed line to $0.03 Ma_{M0}$. The uppercase letters denote the runs.

We find that without magnetic fields, acoustic turbulence obeys a Kolmogorov-type phenomenology, with a nondimensional Kolmogorov prefactor of $C_K \approx 6$. This is significantly larger than the standard Kolmogorov constant for vortical turbulence, which is around 1.6. The presence of a magnetic field lowers this value to around 2–3 for most of our runs, although the universality of this prefactor remains uncertain, as we occasionally observe larger values.

Magnetic fields also influence the partitioning between the acoustic and vortical components of the turbulence. When a non-force-free magnetic field is added, the Lorentz force produces vorticity with a kinetic energy spectrum that is close to equipartition with the magnetic energy spectrum in the upper part of the inertial range. The turbulence also begins to resemble vortical turbulence, developing a spectrum that is nearly in equipartition with the magnetic energy spectrum at high wavenumbers. Our simulations reproduce this process,

in agreement with earlier findings (Kahnashvili et al. 2012).

We also show that even if the magnetic field is force-free, it is still able to produce vorticity by converting acoustic energy into vortical kinetic energy. This conversion is most efficient when the acoustic component has significant contributions from large length scales and when the field is strong. The amplitude of the vortical component in this case is expected to scale quadratically with the magnetic field and linearly with the strength of the initial acoustic component. This scaling is confirmed by our simulations, particularly in Runs N and P, where a strong imposed magnetic field ($Ma_{M0} = 1$) converts acoustic energy into vortical energy. Even in the case of a turbulent magnetic field, the same scaling holds, though the required field strength is much weaker ($Ma_{M1} = 0.005$).

The implications of our findings extend to cosmology, particularly to the early Universe. During the radiation-dominated era, the gas obeys an ultrarelativistic equation of state, where the pressure is proportional to the density, similar to isothermal flows. The sudden generation of acoustic turbulence, for example from cosmological phase transitions (Turner et al. 1992; Hindmarsh et al. 2015), could be converted into vortical turbulence by a magnetic field. Such a field might have been produced either during inflation or during the subsequent reheating era just prior to the radiation-dominated era. This could play a significant role in shaping the dynamics in the early Universe, particularly the generation of vortical turbulence from initially acoustic fluctuations.

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Software and Data Availability. The source code used for the simulations of this study, the PENCIL CODE (Pencil Code Collaboration et al. 2021), is freely available on <https://github.com/pencil-code/Acoustic>.

581 The simulation setups and corresponding input 582 and reduced out data are freely available on
583 <http://norlx65.nordita.org/~brandenb/projects/Acoustic>.

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APPENDIX

662

663 At the end of Sect. 3.4, we mentioned spectral comparisons of Run C with three other runs (Runs E, D, and
 664 G). In Figure 10, we compare the kinetic and magnetic energy spectra for Runs C and E, i.e., with and with-
 665 out initial turbulence. We see that turbulence is gradually being generated by the magnetic field, but there is
 666 hardly any effect on the magnetic energy spectra. We see that turbulence is gradually being generated by the magnetic field, but there is
 667 hardly any effect on the magnetic energy spectra. We see that turbulence is gradually being generated by the magnetic field, but there is
 668 hardly any effect on the magnetic energy spectra. We see that turbulence is gradually being generated by the magnetic field, but there is
 669 hardly any effect on the magnetic energy spectra.

670 In Figure 11, we show the resulting spectra for a case where the induction term, $\mathbf{u} \times \mathbf{B}$, has been suppressed
 671 in Equation (3), i.e., $\iota = 0$, and we just solve the diffusion equation, $\partial \mathbf{A} / \partial t = \eta \nabla^2 \mathbf{A}$. The magnetic field
 672 then decays preferentially at high wavenumbers, where magnetic diffusion acts the strongest. This is evident
 673 from a premature cutoff of the magnetic energy spectrum. The vortical part of the kinetic energy spectrum
 674 now seems to show a very strong bottleneck, but the acoustic part does have a plateau at a low level and a
 675 small bottleneck. This suggests that the initial energy in the acoustic component is unimportant for the dy-
 676 namics of the magnetic field. Moreover, the vorticity production by the magnetic field is largely independent
 677 of the initial energy in the irrotational component. The vortical part of the kinetic energy spectrum
 678 now seems to show a very strong bottleneck, but the acoustic part does have a plateau at a low level and a
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 682 now seems to show a very strong bottleneck, but the acoustic part does have a plateau at a low level and a
 683 small bottleneck. This suggests that the initial energy in the acoustic component is unimportant for the dy-
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 685 of the initial energy in the irrotational component. The vortical part of the kinetic energy spectrum
 686 now seems to show a very strong bottleneck, but the acoustic part does have a plateau at a low level and a
 687 small bottleneck. This suggests that the initial energy in the acoustic component is unimportant for the dy-

688 In Figure 12, we compare magnetic and kinetic energy spectra for the vortical and acoustic components for

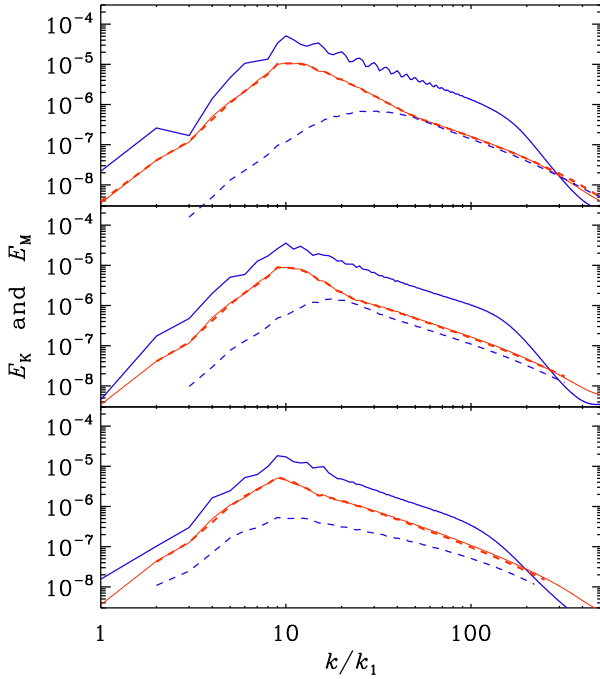


Figure 10. Comparison of kinetic (blue lines) and magnetic (red lines) energy spectra for Runs C (solid lines) and E (dashed lines) at times 2.5, 7.5, and 25, i.e., runs with and without initial turbulence.

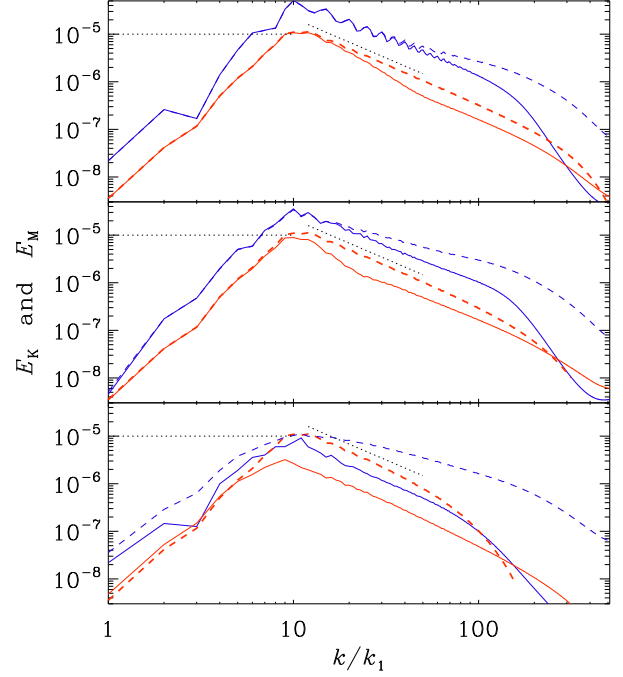


Figure 11. Similar to Figure 10, but for Runs C (solid lines) and D (dashed lines, $\iota = 0$, i.e., no induction) at times 2.5, 7.5, and 60. The black dotted lines provide fixed reference values in each panel.

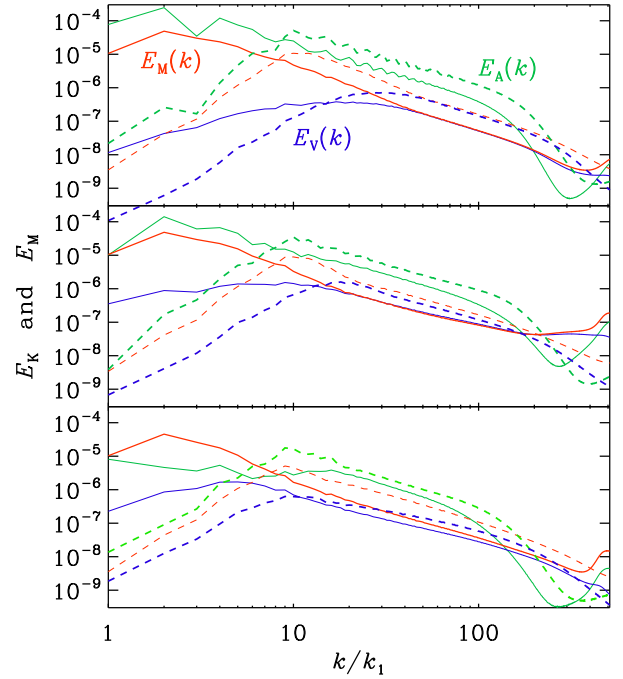


Figure 12. Comparison of acoustic (green lines), vortical kinetic (blue lines), and magnetic (red lines) energy spectra for Runs C (solid lines) and G (dashed lines) at times 2.5, 7.5, and 25.

687 Runs C with G. We see that around the time 7.5, Run C
688 suffers a loss of kinetic energy in the acoustic compo-
689 nents along with a gain of kinetic energy in the vortical
690 component. This energy exchange occurs around the
691 wavenumber $k/k_1 = 2$.